

TOWARD A DATA SONIFICATION DESIGN SPACE MAP

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ABSTRACT

We propose a systematic approach for reasoning about experimental sonification designs for a given type of dataset. Starting from general data properties, the approach recommends initial strategies, and lists possible refinements to consider in the design process. An overview of the strategies included is presented as a mental (and visual) map, and the refinement steps to consider correspond to movements on the map.

The main purpose of this approach is to extract 'theory' from 'observation' (in our case, of design practice), similar to grounded theory in sociology [1]: to make implicit knowledge (often expressed in 'natural' ad hoc decisions by sonification experts) explicit and thus available for reflection, discussion, learning, and application in design work.

This approach is the result of analysing design sessions which took place in an interdisciplinary sonification workshop 'Science By Ear' [2], held in March 2006. In order to explain the concept in practice as well, a set of workshop sessions on one dataset is analysed here in the terms proposed.

[Keywords: Sonification Theory, Sonification Design Strategies]

1. BACKGROUND

When collaborations on sonification for a new field of application start, sonification researchers may know little about the new domain, its common types of data, and its interesting research questions; similarly, domain scientists may know little about sonification, its general possibilities, and its possible benefits for them. In such early phases of collaboration, the task to be achieved with a single particular sonification is often difficult to define clearly, so it makes sense to employ an exploratory strategy which allows for mutual learning and exchange. Eventually, the interesting tasks to achieve become clearer in the process.

Rheinberger describes in [3] that researchers deal with 'epistemic things', which are by definition vague at first (they can be e.g. physical objects, concepts or procedures whose usefulness is only slowly becoming clear); they choose 'experimental setups' (ensembles of epistemic things and established tools, devices, procedures), which allow for endless repetitions of experiments with minimal variations. The differential results gained from this exhaustion of a chosen area in the possibility space can allow for new insights. Then, an experimental setup can collapse into an established device or practice, and become part of a next experimental setup.

From this perspective, sonification designs start their lifecycle as epistemic things, which need to be refined under usage; they

may in time become part of experimental setups, and if successful, eventually 'disappear' as established scientific tools.

1.1. Some Working Definitions

The objects or 'content' to be perceptualised can be well-known information, or new unknown data (or shades of gray in between). The aims for these two applications are very different: for information, establishing easy-to-grasp analogies is central, for data, enabling the perceptual emergence of latent phenomena in the data. As working terminology for the context here, we propose to define the following three terms:

Auditory Display is the rendering of data and/or information into sound designed for human listening. This is the most general, all-encompassing term (even though the term 'display' has a visual undertone to it).

We further propose to differentiate between two subspecies of Auditory Displays:

Auditory Information Display is the rendering of well-understood information into sound designed for communication to human beings. It includes speech messages such as in airports and train stations, auditory feedback sounds on computers, alarms and warning systems, process monitoring systems, etc.

Sonification or *Data Sonification* is the rendering of (typically scientific) data into (typically non-speech) sound designed for human auditory perception. The informational value of the rendering is often unknown beforehand, particularly in data exploration.

This paper focuses on Data Sonification in the narrower sense.

1.2. Common Sonification Strategies

The literature often classifies sonification approaches into Audification, Parameter Mapping [4] and Model-Based Sonification [5]. For the context here, we prefer slightly different categories, which will become clear along the way; so, our three most common approaches are: Sonification by Continuous Data Representation, by Discrete Point Data Representation, and by Model-Based Data Representation.

Continuous Data Representation treats data as quasi-analog continuous signals, and relies on two preconditions: equal distances along at least one dimension, typically time and/or space; and sufficient (spatial or temporal) sampling rate, so that interpolation between data points is meaningful. Both simple audification and parameter mapping onto continuous sounds belong in this category.

Its advantages include: subjective perceptual smoothness; interpolation can make the sampling interval (which is an observation artifact) disappear; perception of continuous shapes (curves) can be appropriate; audition is very good at structures in time.

Its drawbacks include: it is often tied to linear movement along one axis only; and events present in the data (e.g., global state changes in a system) can be difficult to represent well.

Discrete Point Data Representation creates individual events for every data point, one can easily arrange the data in different orders, choose subsets based on special criteria (e.g., based on navigation input), and when special conditions arise, they can be expressed well.

Its advantages include: more flexibility, e.g., random iterations over data subsets; and the lack of illusion of continuity may be more accurate to the data.

Its drawbacks include: attention may be drawn to data independent display parameters, such as a fixed grain repetition rate; and at higher data rates, some of the advantages may not apply.

Model-Based Data Representation employs more complex mediation between data and sound rendering by introducing a model, whose properties are informed by the data.

Its advantages include: domain knowledge can be captured and employed in the model; and models may be applicable to multiple types of datasets.

Its drawbacks include: assumptions built into models may introduce bias leading away from domain understanding; there may be a sense of disconnection between data and sound results.

2. THE SONIFICATION DESIGN SPACE MAP

Task/Data Analysis [6] focuses on solving well-defined auditory information design problems: How to design an Auditory Display for a specific task, based on systematic descriptions of the task and the data. Here, the phenomena to be perceptualised are known beforehand, and one tries to render them as clearly as possible.

The Sonification Design Space Map given here addresses a similar but different problem: The aim to be achieved here is to find transformations that let structures/patterns in the data (which are not known beforehand) emerge as perceptual entities in the sound which jump to the foreground, i.e., as identifiable 'interesting audible objects'; in the electronic music field, these are called 'sound objects' (from '*objets sonores*' [7]), in psychoacoustics literature, 'auditory gestalts' (e.g. [8]).

In other words, the most general task in sonifications is to detect auditory gestalts in the acoustic representation, which one assumes correspond to any patterns and structures in the data one wants to find.

2.1. The Map Axes

To facilitate this search for the unknown, the Design Space Map enables a designer or researcher to engage in systematic reasoning about applying different sonification strategies to his/her task or problem, based on data dimensionality and perceptual concepts.

Especially while the task is not yet clearly understood and defined (which is often the case in exploratory contexts), reasoning about data aspects, and making well-informed initial choices based on perceptual givens can help to develop a clearer formulation of useful tasks.

So, the proposed map of the Sonification Design Space (see figure 1) has these axes:

X-axis : the number of data points estimated to be involved in one gestalt, or 'expected gestalt number';

Y-axis : the number of properties of interest of each data point, i.e., the number of data dimensions to be employed;

Z-axis : the number of streams estimated to be suitable for meaningful data representation.

To ensure that the auditory gestalts of interest will be easily perceptible, the most fundamental design decision is the time scale: In auditory gestalts (or sound objects) of 100 msec and less it becomes more and more difficult to discern meaningful detail, while following a single gestalt for longer than say 30 seconds takes great concentration; thus, a reasonable first order of magnitude for a good time frame for single gestalts is the duration of echoic memory, i.e., roughly 1-3 seconds [9]. The 'expected gestalt number' is the number of data points (of the dataset under study) that should be represented within this chosen time frame to allow for perception of individual gestalts within data subsets. Note that the three-second time frame does not necessarily limit the number of data points represented: the micro-time scale is a fascinating area for creating sound that is rich in detail and expressive [10].

2.2. The Map Zones

The zones shown in the figure 1 do not have hard borders; their extensions are only meant to give an indication how close-by (and thus meaningfully applicable) which strategies are for what data 'gestalt number'. Similarly, the number ranges given below are only approximate orders of magnitude, and mainly based on personal experience in electronic music and sonification.

The Discrete-Point Zone ranges roughly from gestalt numbers 1 - 1000 and from properties numbers 1 - 20; the transition shown in the map from Note-like percepts via Textures to granular events which merge into Clouds is mainly perceptual.

The Continuous Zone ranges roughly from gestalt numbers 10 - 100.000 and from properties numbers 1 - 20; the main transition here is between Parameter Mapping and Audification, with various technical choices indicated along the way, such as using the continuous data signal as Modulation Source, Band Splitting, and applying Filtering.

The Model-Based Zone ranges roughly from gestalt numbers 10 - 50.000 and from properties numbers 8 - 128; because the approach is so general, there are no further orientation points in it yet. Existing varieties of model-based approaches are still being analysed in the terms of this Sonification Design Space, and will then be integrated in appropriate locations on the map.

3. REFINEMENT BY MOVING ON THE MAP

In the evolution of a sonification design, the intermediate versions can be conceptualised easily as locations on the map, based on how many data points are rendered into the basic time interval, how many data dimensions are being used in the representation, and how many perceptual streams are in use. A step from one version to the next can then be considered analogous to a movement on the map. This mind model aims to capture the design processes we could observe in the Science by Ear workshop (in this paper, SBE for short) [1].

3.1. Data Anchor

For exploring a dataset, one can start by putting a reference point on the map, which we call the Data Anchor: This is a point on the map corresponding to the full number of data points and data dimensions. A first synopsis, or better *Synakusis*, of the entire dataset (within the time interval of ca. 3 seconds) can then be

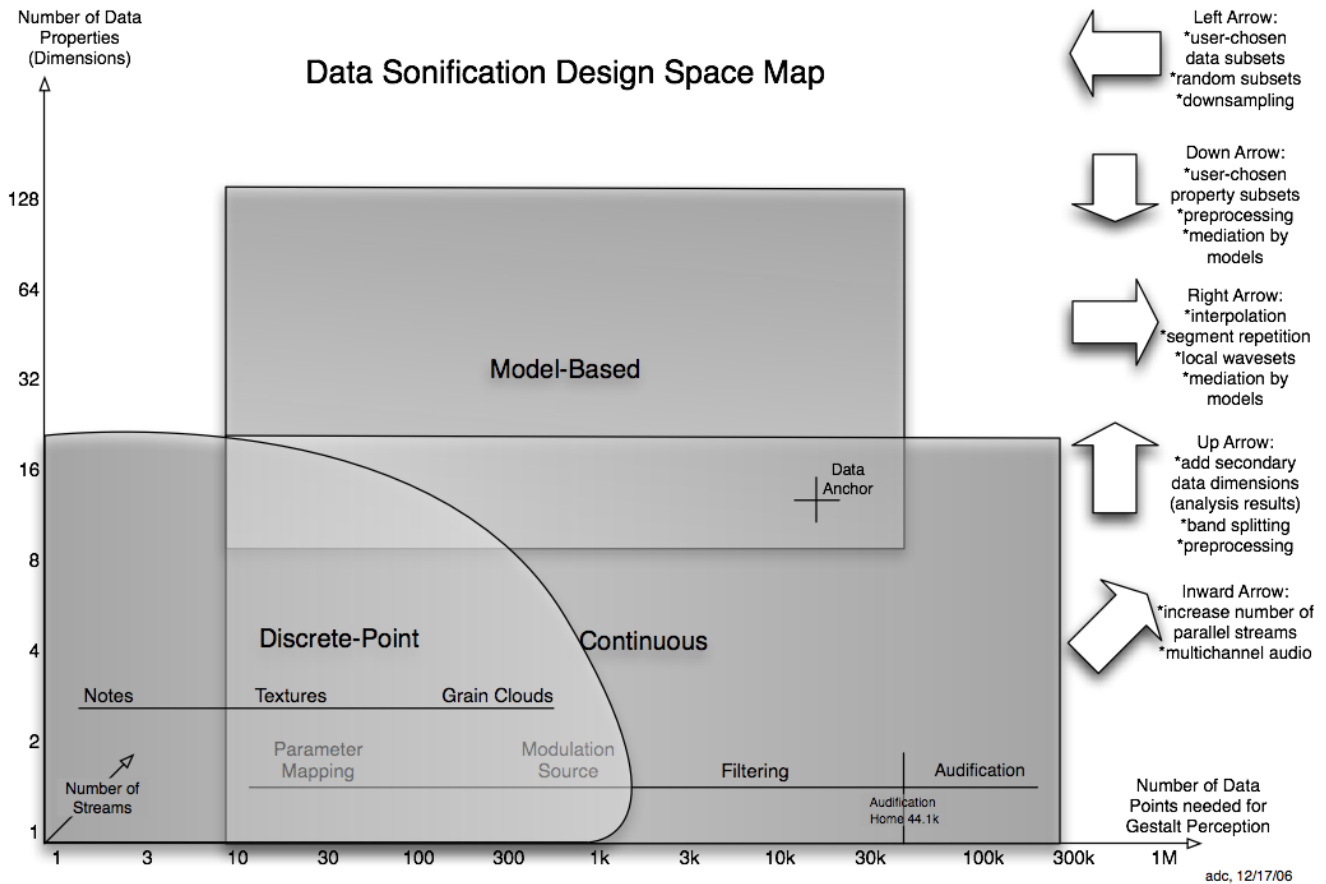


Figure 1: The Data Sonification Design Space Map. The overlapping zones are fuzzy areas where different sonification approaches apply; the arrows on the right refer to movements on the map, which correspond to design iterations. For detailed explanations see section 2.

created with one of the nearest sonification strategies on the map. Subsequent sonification designs and sketches will typically correspond to a movement down from this point (i.e., toward less dimensions) and to the left (toward less than the total number of data points).

3.2. Shift Arrows

Shift Arrows, as shown in Fig.1 on the right hand side, allow for moving one's current 'working position' on the Design Space Map, in order to employ different sonification strategies in the exploration process. Note that some shifting operations are used for 'zooming', and leave the original data untouched, while others employ data reduction, extension, and transformation; in any sonification design one develops, it is essential to differentiate between these and document the steps taken clearly. Finally, one can decide to defer such decisions and open them for interaction, so that, e.g., subsets are selected interactively.

A *left-shifting arrow* can be used to reduce the assumed 'gestalt number', in effect using less data points within the presentation time frame. Some options are: investigating smaller, user-chosen data point subsets (this can be by means of interaction, e.g. 'tapping' on a data region and hearing that subset); downsampling, e.g. linear, averaging, bandlimited, or by random subsets; and other

forms of data preprocessing.

A *down-shifting arrow* can be used to reduce the 'properties number', i.e., to employ less data properties (or dimensions) in the presentation. Some options are: dimensionality reduction by preprocessing (e.g., statistical approaches like Principal Component Analysis (PCA) or Multidimensional Scaling (MDS), or using locality-preserving space-filling curves, e.g., Hilbert curves); and user-chosen data property subsets, keeping the option to explore others later. (Model-based sonification concepts may also involve dimensionality reduction techniques, yet they are in principle quite different from mapping-based approaches.)

An *up-shifting arrow* can be used to increase the number of properties used in the sonification design; e.g., for better discrimination of components in mixed signals, or to increase 'contrast' by emphasizing aspects with relevance-based weighting. Some options are: band-splitting time series data into frequency bands can increase detail resolution; using the amplitude envelope of a signal to accentuate its dynamic range; other domain-specific forms of preprocessing may be appropriate for adding secondary data dimensions to be used in the sonification design.

A *right-shifting arrow* can be used to increase the number of datapoints used, which can help to reduce representation artifacts. Some options are: interpolation of signal shape between data points; repetition of data segments (e.g., granular synthesis with

slower-moving windows); local waveset audification; and model-based sonification strategies can be used to create e.g. physical vibrational models, whose state may be represented in larger secondary datasets informed by comparatively few original data points.

Interpolation in time-series data is often employed habitually without further notice; the model given here allows for notating this transformation as a right-shifting arrow. If one is certain that the sampling rate used was sufficient, using cubic (or better) interpolation instead of the actually measured steps creates a smoother signal which is nearer to the phenomenon measured than the sampled values. When such a smoothed signal is used for modulating an audible synthesis parameter, the potentially distracting presence of the time step unit should be less apparent.

3.3. Third Dimension Shifts

So far, all arrows have concerned movement in the front plane of the map, where only a single auditory stream is used for data representation. After the time scale, the number of streams is the second most fundamental perceptual design decision. By putting some data dimensions into parallel auditory streams (especially data dimensions of the same type, such as time-series of EEG measurements for multiple electrodes), overall display dimensionality can be increased in a straightforward way, while dimensionality in each individual stream can be lowered substantially, and thus becomes easier to perceive. (The equivalent movement is difficult to represent well visually on a 2D map, but easy to imagine in 3D space.) For multiple streams, all previous arrow movements apply as above, and two more arrows become available:

An *inward arrow* can be used to increase the number of parallel streams in the representation. Some options are: multichannel audio presentation; and setting one perceptual dimension of the parallel streams to fixed values with large enough differences to cause stream separation, thus in effect labelling the streams.

An *outward arrow* can be used to decrease the number of parallel streams in the representation. Some options are: selecting fewer streams to listen to; intentionally allowing for perceptual merging of streams.

Fusion between streams can be an appropriate expression of data features, e.g., in EEG recordings, massive synchronisation of signals across electrodes may cause the streams to fuse, which can represent the nature of some epileptic seizures well.

4. EXAMPLES FROM 'SCIENCE BY EAR'

In order to clarify the theoretical considerations given so far, we now turn to analysing design work done in an interdisciplinary setting. We report one exemplary set of design sessions as they happened, with added after-the-fact analysis in terms of the Sonification Design Space Map concept (short: SDSM). Where SDSM strongly calls for additional designs, these are provided and marked as additions. This is intended to demonstrate the potential of going from practice-grounded theory back to theory-informed practice.

4.1. Workshop Setting

True to the inherently interdisciplinary nature of scientific data sonification, the SBE workshop brought together three groups of people for three days: Domain scientists who were invited to supply data they usually work with; an international group of sonification experts; and audio programmers/sound designers. Apart from invited talks by the sonification experts, the main body of work

consisted of sonification design sessions, where interdisciplinary groups (ca. 8 people, domain scientists, sonification experts, programmers, and a moderator) spent 2 hours discussing one submitted data set, experimenting with different sonification designs, and then discussing results across groups in plenary meetings.

In each session, discussion notes were taken as documentation, where possible the sonification designs were kept as code, and all the sound examples played in the plenary meetings were rendered as audio files. All this documentation is available online at [2].

4.2. Load Flow - TaskData Analysis

This particular submitted data set came from electrical power systems, capturing electrical power usage for one week (December 18 - 24, 2004) across 5 groups of power consumers: households, trade and industry, agriculture, heating and warm water, and street lighting; a sum over all consumer groups was also provided.

Clear daily cycles were to be expected, as well as changes between workdays and weekends/holidays. While this is not scientifically challenging, it is a good example of simple data with everyday relevance. We chose this dataset for the first parallel session, and it did serve well for exploring basic sonification concepts with novices. The full documentation for these sessions is available online here¹.

The dataset was an excel file with 5 columns for the consumer groups, and consumption values were sampled at 15 minute intervals; so for a week, $24 * 4 * 7 = 672$ data points for the entire dataset. In SDSM terms, this puts the Data Anchor for this set right in the middle of the Design Space Map, in the overlap zone between Discrete-Point and Continuous Sonification.

4.3. Sonification Designs

All sonification designs are shown on the Design Space Map in figure 2 as A1, B1, C3 etc. Teams A and B used SuperCollider3 for the design sketches, Team C worked with PureData.

4.3.1. Team A

Team A began by sonifying the entire dataset as five parallel streams, scaled to 13 seconds, i.e. one day scaled to ca. 2 seconds; power values were mapped to frequency [A1]².

After experimenting with larger/smaller timescales, agreement was reached that the initial choice of timescale was appropriate and useful. In SDSM terms, this is looking for auditory gestalts at the scale of single days. As SDSM recommends starting with a *synakusis* into a timeframe of 3 seconds, this is provided here [A+]³. Note that this was added after the workshop.

Then, alternative sound parameter mappings were tried out:

[A2] Mapping powers to amplitudes of five tones labeled with different pitches⁴. This did not work well, as one could not distinguish much shape detail in amplitude changes.

[A3] Mapping powers to amplitudes and the cutoff frequencies of resonant lowpass filters of five differently pitched tones⁵. This was clearer, but still not as useful as mapping to tone frequencies.

¹<http://sonenvir.at/workshop/problems/loadflow>. All sound examples can be found here, in the folders TeamA, TeamB, TeamC, and Extras; to save space, relative links at this site are given as .teamX/file.mp3 etc.

² ./Team_A/TeamA_1_FiveSines_PowersToFreqs.mp3

³ ./extras/LoadflowSynakusis.mp3

⁴ ./Team_A/TeamA_2_FiveTones_PowersToAmps.mp3

⁵ ./Team_A/TeamA_3_FiveTones_PowersToAmpsAndFilterfreqs.mp3

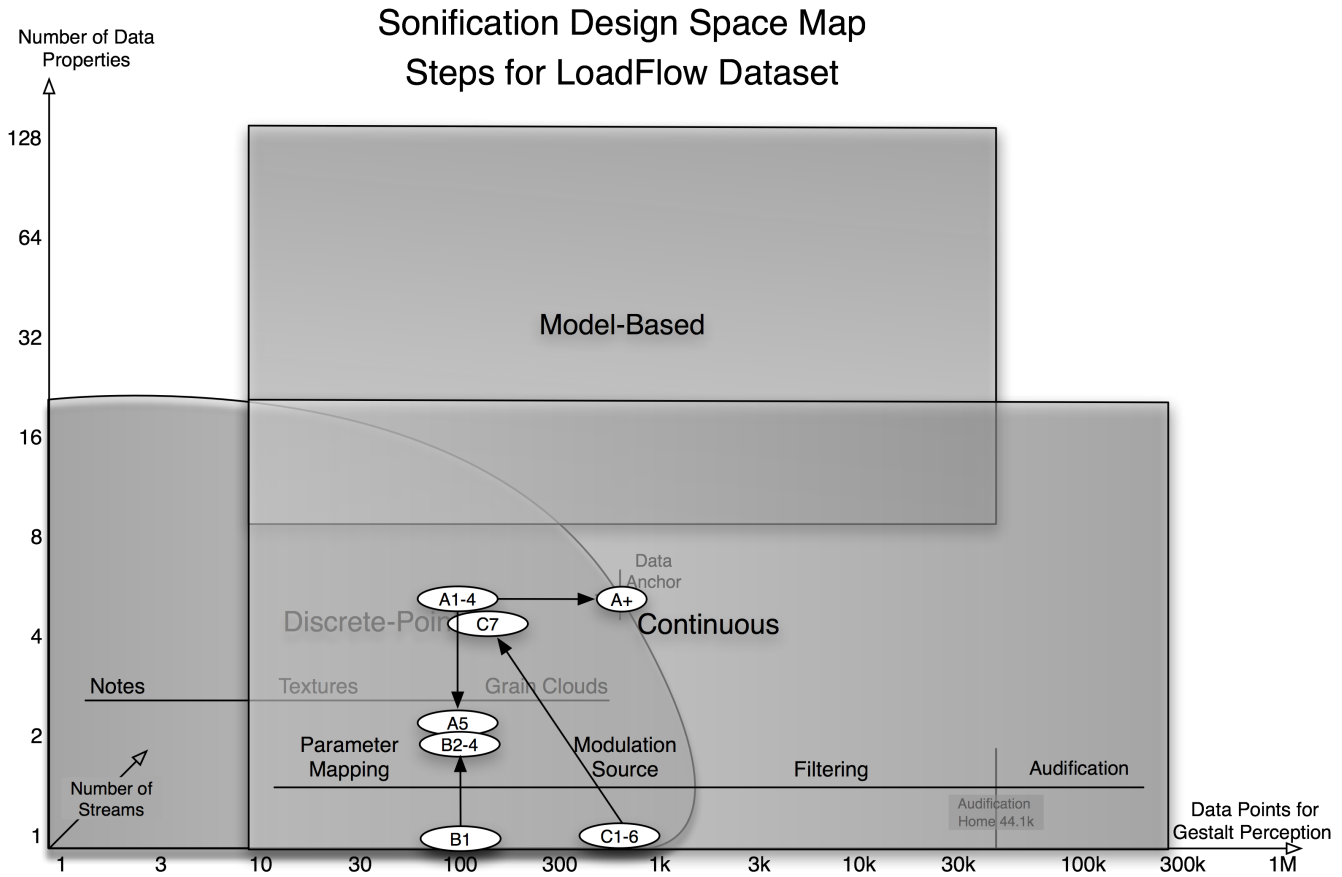


Figure 2: All design steps taken by the 3 teams for the loadflow dataset as locations and arrows.

[A4] Going back to mapping to frequencies, each tone was labeled with a different phase modulation index⁶. While this allowed for better stream identification, the (quickly chosen) scaling was not deemed very pleasant, if inadvertently amusing.

[A5] Finally, the team tried using less parallel streams, and adding secondary data: the phase modulation depth (basically, the brightness) of both channels (household and agriculture) was controlled from the difference between the two data channels⁷. While this did not work very well, it seemed promising with better secondary data choices; however, at this point session time was over. In SDSM terms, design A5 is a move down - to less channels - and a move back up - derived data used to control additional parameters (the map only shows the resultant move).

4.3.2. Team B

Team B chose to do audification (following one sonification expert's request), and to use an interactive sonification approach: Their design loaded the entire data for one channel (672 values, equal to one week of data time) into a buffer, and played back a movable 96-value segment (equal to one day) as a looped waveform. The computer mouse position was used to control which

24hour-segment is heard at any time⁸.

While the team found the data sample rate and overall data size was too low for much detail, an interesting side effect turned up: when audifying segments in this fashion, the difference between the same time of day for two adjacent days was emphasized; large differences at specific times between adjacent days created strong buzzing⁹. In the next design step, 2 channels, households (left) and agriculture (right) were compared side by side¹⁰, and for clearer separation, they were labeled with different loop frequencies¹¹. The final design example maps the power values corresponding to the current mouse position directly to the amplitude of a 50Hz (European mains frequency) filtered pulse wave¹². As above, in the fixed rendering here, the mouse moves thru the week at constant speed within 14 seconds.

In SDSM terms, the initial choices were to move all the way down on the map (only 1, then 2 out of 5 channels at a time), and a move to the left: a user chosen data subset was played by moving a one-day window within the data. Note that this move is actually creating an interaction parameter for sonification design users, which is one the many advantages of current interactive program-

⁸For the non-interactive sound examples, the mouse is moved automatically through the week within 14 seconds.

⁹./Team_B/1_LoadFlow_B_Households.mp3

¹⁰./Team_B/2_LoadFlow_B_households_agriculture.mp3

¹¹./Team_B/3_LoadFlow_B_households_agriculture.mp3

¹²./Team_B/4_LoadFlow_B_households_agriculture.mp3

⁶./Team_A/TeamA.4.FiveFMSounds_IDbyModDepth.mp3

⁷./Team_A/TeamA.5.TwoFMSounds_DiffToModDepth.mp3

ming environments.

Note that the interpolation commonly used in audification is actually slightly dubious here: There may well have been meaningful short-time fluctuations within 15 minute intervals which would not be captured in the data as supplied.

4.3.3. Team C

Team C used PureData as programming environment. Their approach was quite similar to Team A, with interesting differences: They began with scaling each single data channel into 3 seconds, mapping power in that channel both to frequency and to amplitude, and subsequently rendered all channels in this fashion¹³. Finally, this team also produced a version with six parallel streams (including the sum value), scaled into 12 seconds, and with different timbres¹⁴.

In SDSM terms, they first moved to the bottom of the map, while keeping full data scale, i.e. a *synakusis*-sized time window; example 7 moves back up (using all channels), and to the left (i.e., toward higher time resolution, gestalts on the order of single days of data).

5. CONCLUSIONS

Conceptualising the sonification design process in terms of movements on a design space map, one can experiment freely by making informed decisions between different strategies to use for the data exploration process; this can help to arrive at a representation which produces perceptible auditory gestalts more efficiently and more clearly. Understanding the sonification process itself, its development, and how all the choices made influence the sound representation one has arrived at, is essential in order to attribute perceptual features of the sound to their possible causes: They may express properties of the dataset, they may be typical features of the particular sonification approach chosen, or they can be artifacts of data transformation processes used.

As the analyses of some sonification design sessions show, the terminology and map metaphor provide valuable descriptions of the steps taken; having the map available (mentally or physically) for a design work session seems very likely to provide good clues for next experimental steps to take.

Note that the map is open to extensions: As new sonification strategies and techniques evolve, they can easily be classified as either new zones, areas within existing zones, or as transforms belonging to one of the arrows category; then their appropriate locations on the map can easily be estimated and assigned.

6. FUTURE WORK

There are several ways to extend the map and make it more useful:

Gaining a more detailed understanding of model-based sonification, and expressing that understanding in the terms of the conceptual framework of the map.

More and richer detail can be added, e.g., by analysing the steps taken in observed design sessions, classifying them as strategies, and adding them if new or different. (This is in progress for a future publication.)

Expertise can be integrated by interviewing sonification experts, tapping into their experience, inquiring about their favorite

strategies, or decisions they remember that made a big difference for a specific design process.

One can imagine building an application that lets designers navigate a design space map, on which simple example data sets with coded sonification designs are located. When one moves in an area that corresponds to the dimensionality of the data under study, the nearest example pops up, and can be adapted for experimentation with one's own data. The examples should obviously capture established sonification practice and guidelines, e.g., concerning mapping [11].

Finally, many of the strategies need not be fixed decisions made once; being able to make many of the strategic choices interactively when exploring a dataset would be both exciting and extremely valuable.

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¹³./Team_C/TeamC_Channel1.mp3 to./Team_C/TeamC_Channel6.mp3

¹⁴./Team_C/TeamC_AllChannels.mp3